

# Mitigating Mining-Induced Hazards

A Continuous Surface Monitoring System using Kriging

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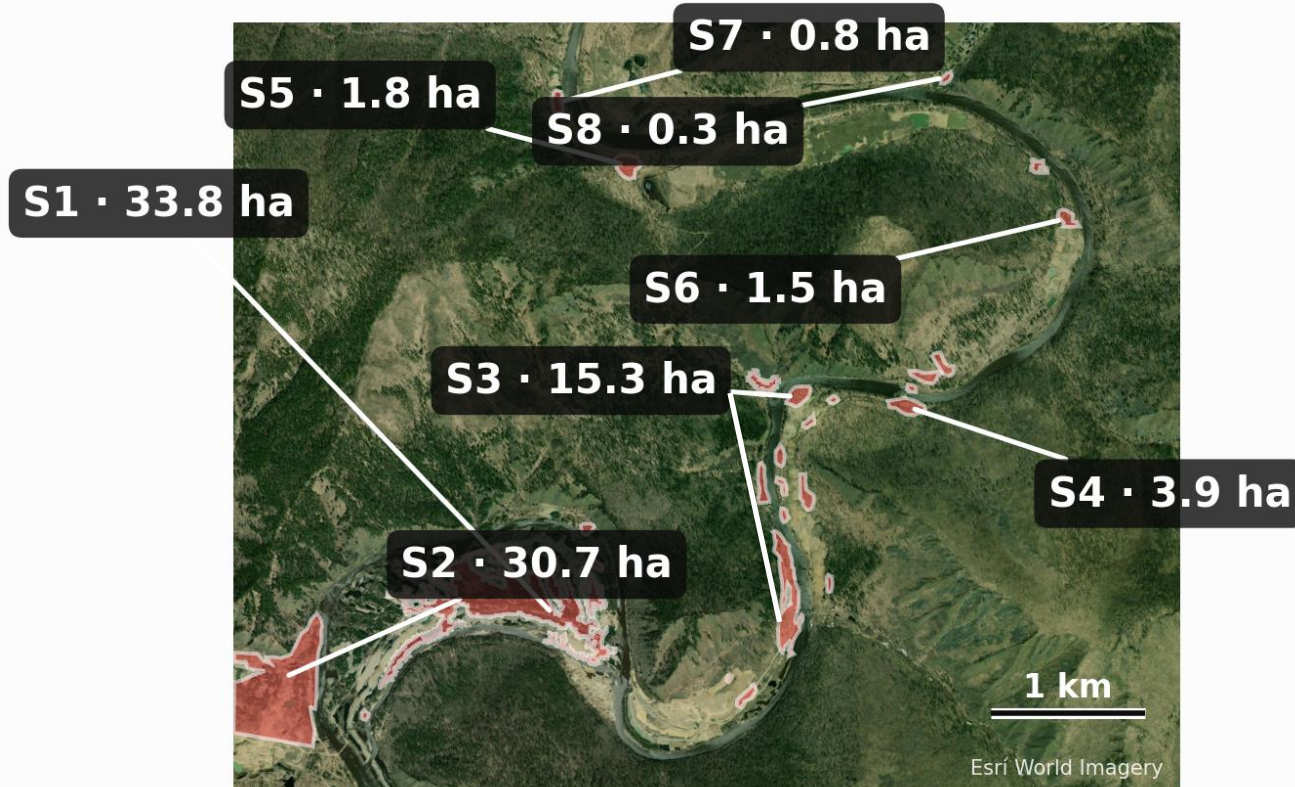
# Extraction outpaces oversight

- Exploration and extraction routinely proceed without the required inspections or ecological assessment.
- Not only unauthorized operations, **licensed activity outruns its checks too.**
- What is left behind **migrates into rivers and pastures long after work stops.** [1][2]
- Remediation costs exceed prevention **by orders of magnitude.**

# What a continuous monitor has to do

- Run on **free, routinely updated imagery**, or it cannot be continuous.
- Catch **new, small** disturbance **early**, and separate it from **natural seasonal change**.
- Build a **longitudinal record**: early warning, dated evidence, and later verification of rehabilitation.

The demonstration area: 30.6 km<sup>2</sup> of the Eroo,  
eight sites



## What the disturbance looks like

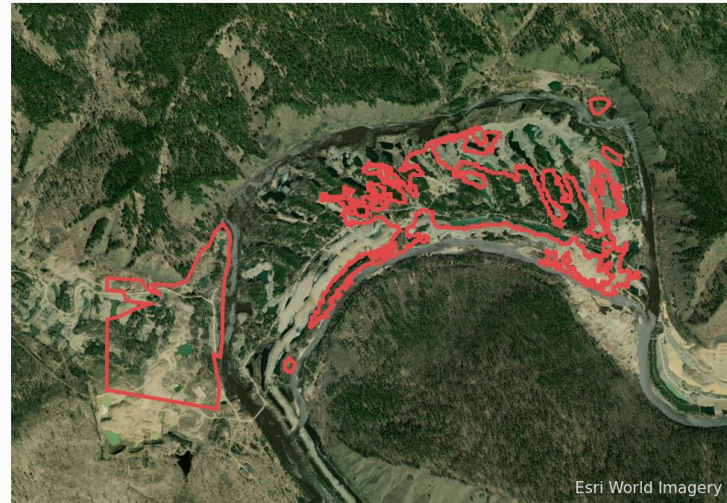
Braided pits and spoil along the channel, unmistakable once large.

**The southwest complex — braided pits and spoil along the channel, the shape the monitor has to find while it is still small**

the imagery



labelled extent — S1 + S2, 64 ha

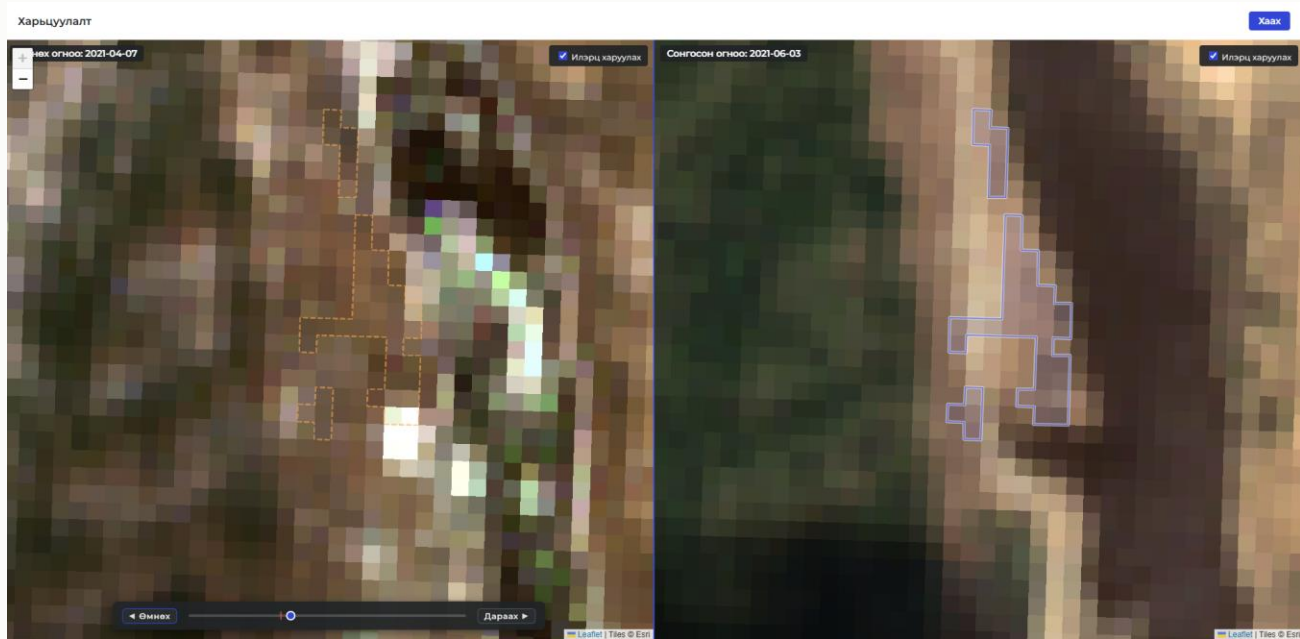


## Why this is hard to predict

At 10 m, a fresh cut is **a handful of pixels**.

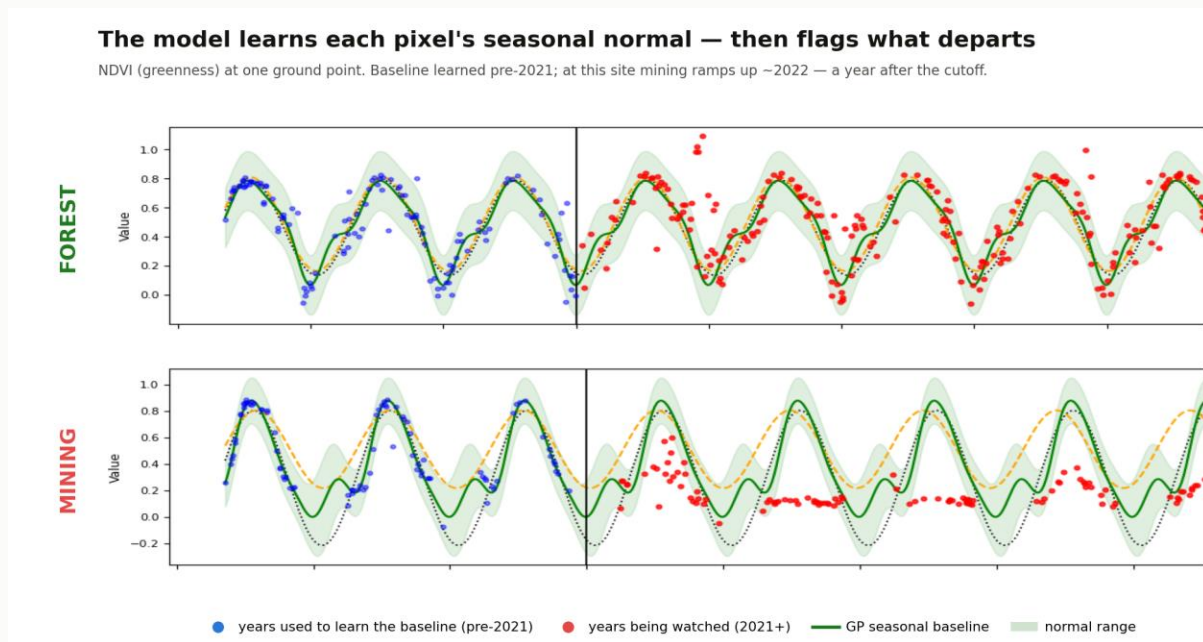
In any single image it looks like dry grass or river gravel.

The valley greens and browns each year, **“change” alone is not disturbance**.



## A self-learned baseline per pixel

Every pixel learns **its own seasonal rhythm** [4][5], a kriging baseline with a normal range. The kernel is locked: **one-year** periodic, **five-year** trend. A step change cannot be absorbed. **Unsupervised**, nothing to train, nothing to port to a new region. [3]

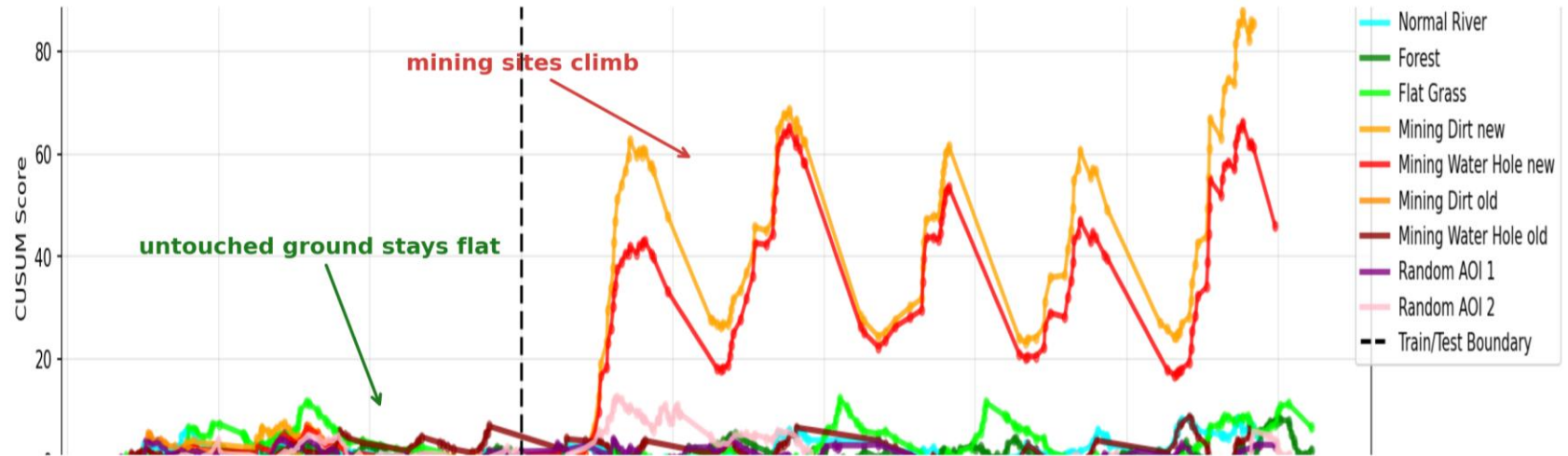


## Telling disturbance apart from nature

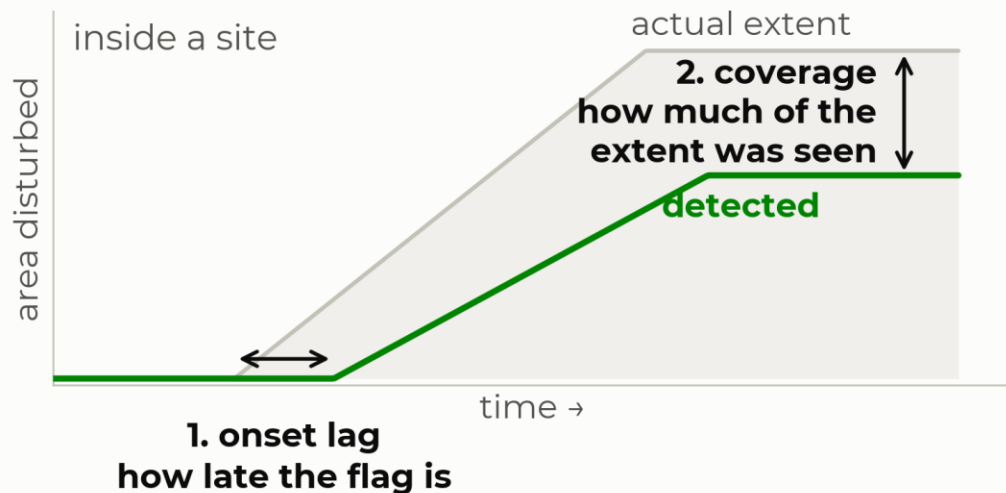
One off-band observation is not a strong evidence evidence, cloud and haze do that too.

Cumulative disturbance score climbs away; forest, grass and river stay flat, **with no per-site tuning**.<sup>[6]</sup>

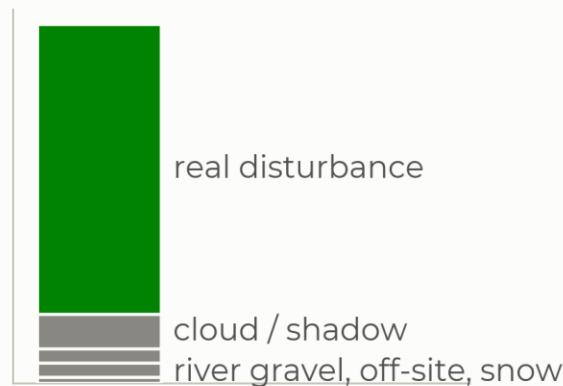
Accumulated anomaly score (NDVI). Each line is one landmark; higher = more sustained departure from its baseline.



# How do you grade a monitor?



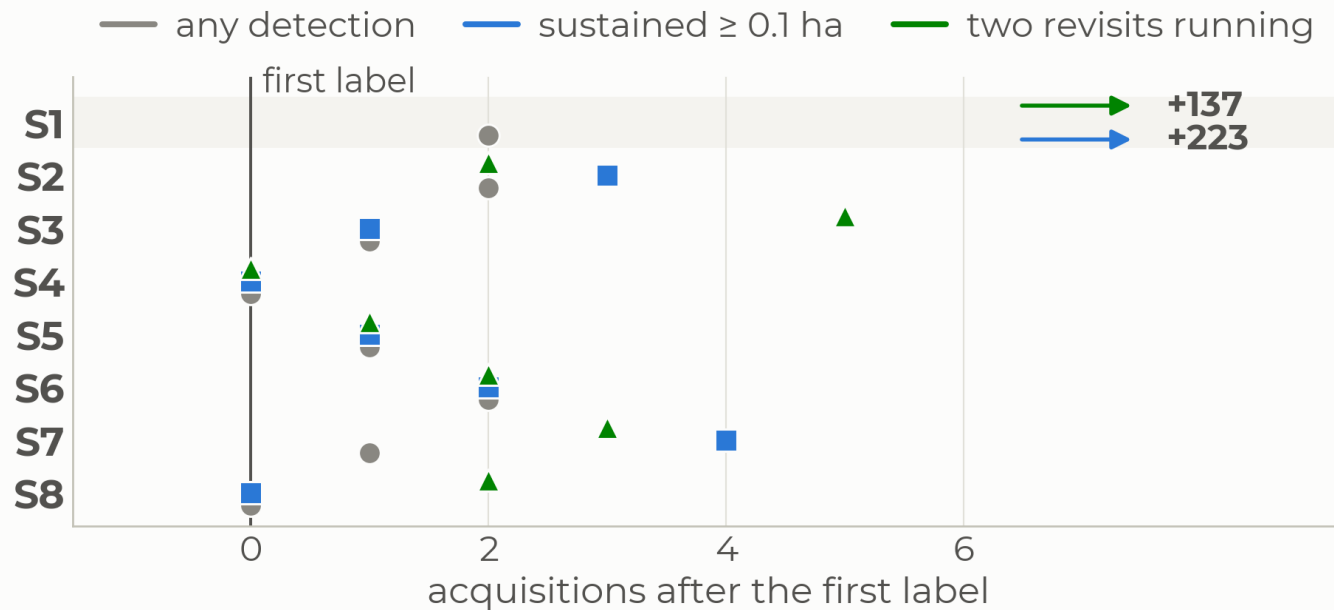
## 3. error budget every detection, by cause



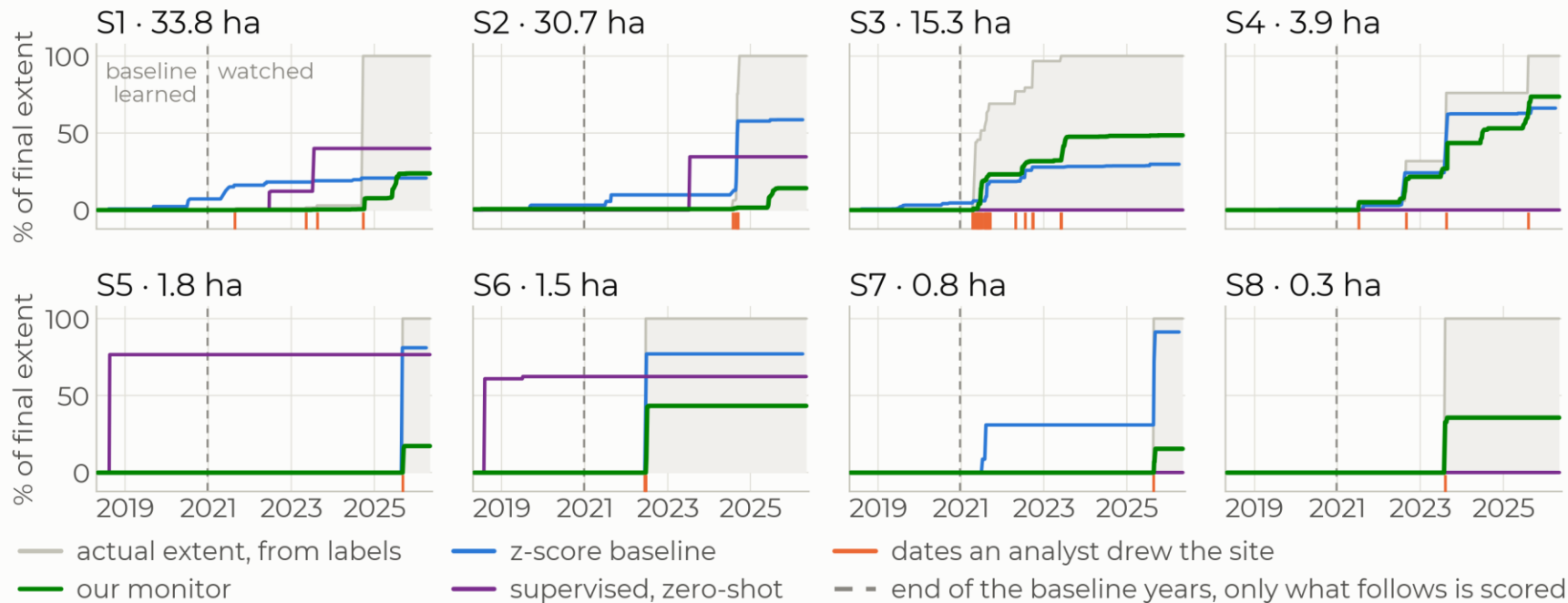
## Is it on time?

Strictly **out of sample**: baseline learned pre-2021, everything scored 2021–2026.

**Every site flagged within ~two timesteps of data**, median one.



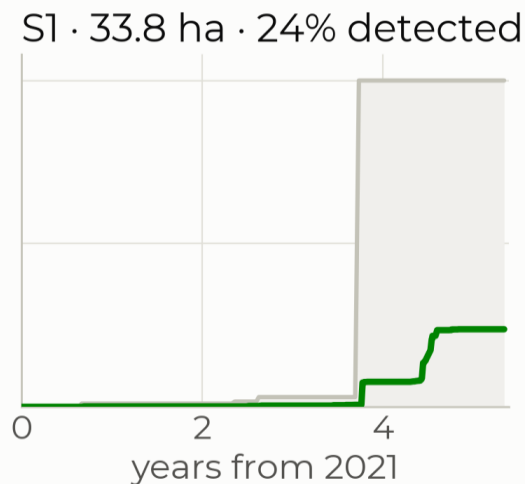
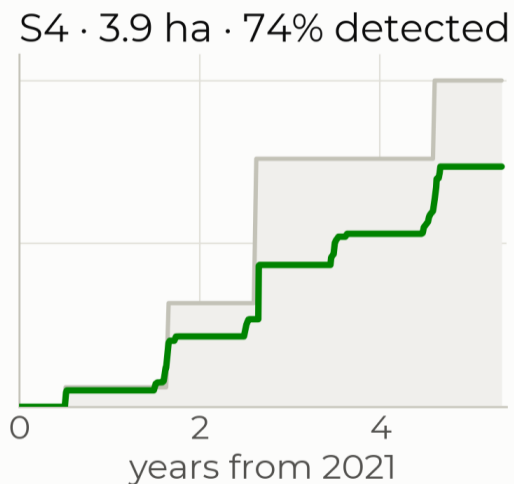
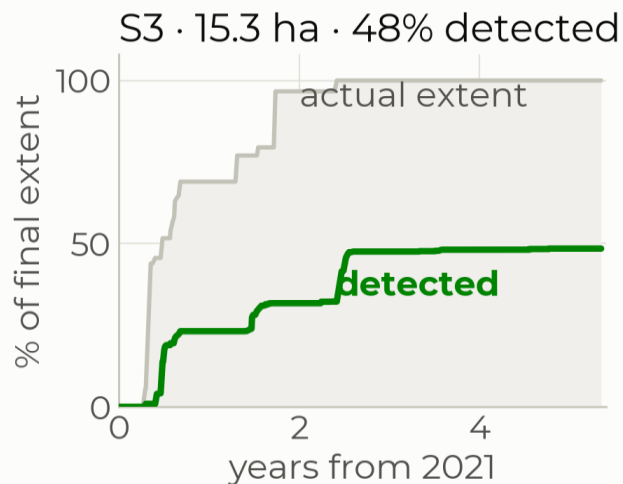
# Every site, every detector



## Does it trace the extent?

Partial by design: the monitor pings the active face, it does not trace the whole pit.

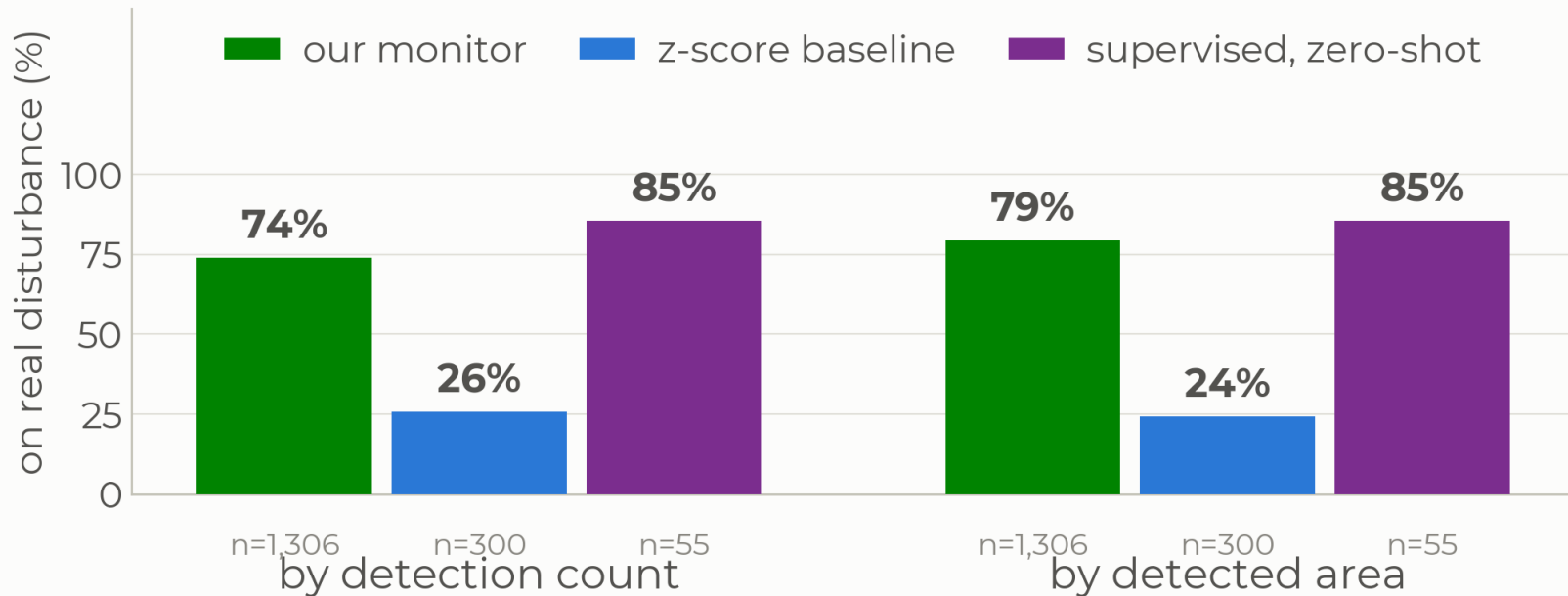
Acceptable for an alert, but only if we **say so** rather than quietly scoring ourselves on presence.



## Three detectors, one basis

**3× more** of ours lands on real disturbance than the z-score's.

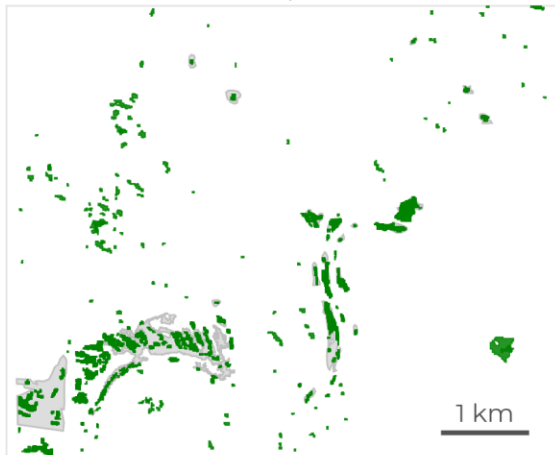
The supervised model AMW [7] leads on precision. Coverage is the next slide.



# Map comparison view.

## GP monitor

1,306 detections · 1,210 places · 0.13 ha each



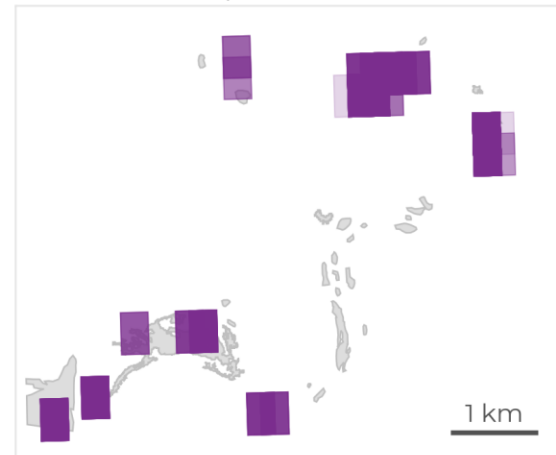
## z-score

300 detections · 300 places · 1.67 ha each



## AMW

55 detections · 7 places · 15.05 ha each



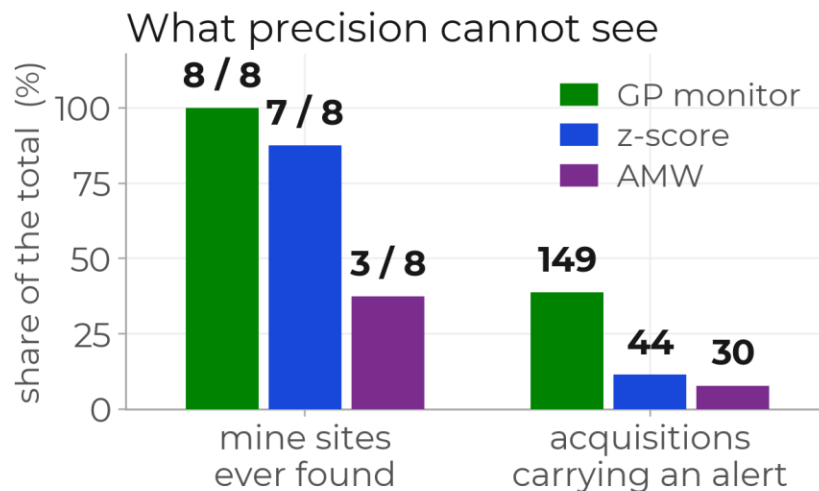
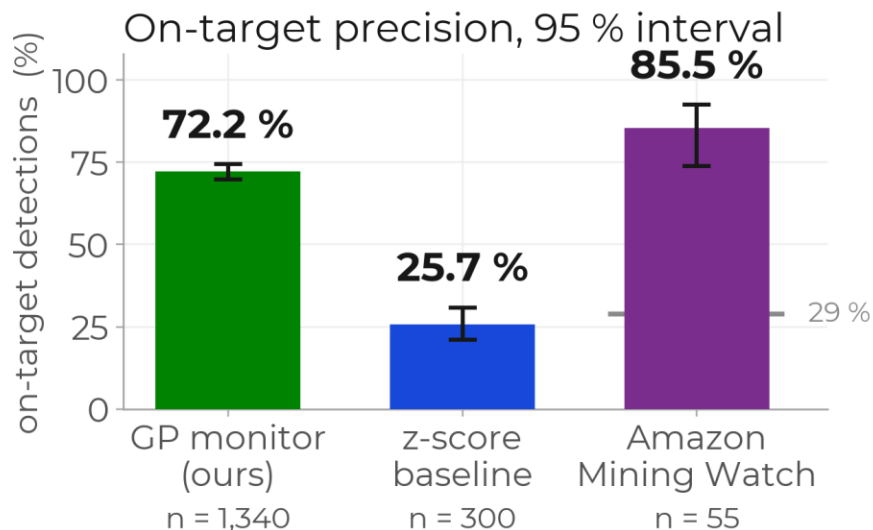
Grey = analyst-labelled mining; pale purple = AMW inside the training window, not scored. Over the whole record AMW returned 269 patches on only 22 distinct 480 m cells: repeat firings on the same ground, not new places.

## Against a supervised model

Amazon Mining Watch [7], a supervised CNN, re-run on **our grid**.

**The most precise detector here: 85.5 % against our 57.4 %.**

It reaches **three of eight sites** and paints **828 ha** doing it. We flag 176.



Reporting precision without coverage inverts the ranking.

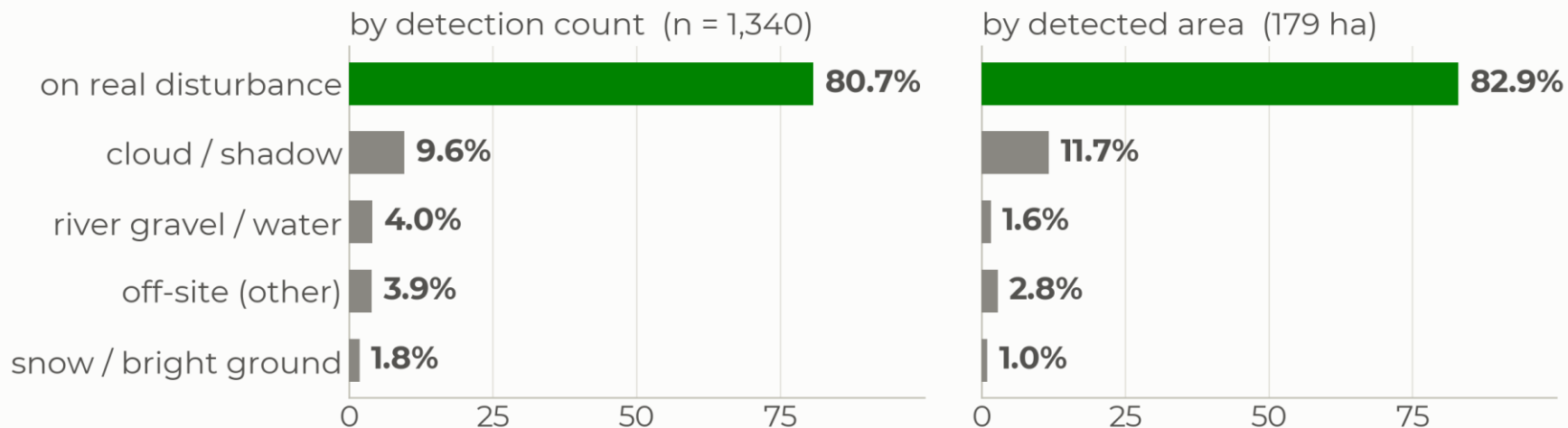
On-target = touching labelled mining or ground a reviewer confirmed as mining.  
n includes the 34 detections a late audit reclassified as errors.

## What it gets wrong

Every off-label detection was clustered and **reviewed in context**, then given a cause.

**Cloud and snow are 11 %** with a known fix; river gravel adds 4 %. Unexplained residual  $\approx 4 \%$ .

Honest caveat: only **53 % of detected area** sits strictly inside a mapped site.



# Where this goes next

- **Filter the known noise.** Cloud, snow and river gravel are named, recurring and maskable, 15 % of detections with a known remedy.
- **Make it cheap to scale.** Cost per km<sup>2</sup> is a research constraint, not an engineering afterthought.
- **More observations along the time axis.** The binding limit: the alert needs ~2 *usable* timesteps of data acquisition.

# What we cannot yet claim

- **One basin, eight sites.** The design argues the method transfers; not yet *demonstrated* on a second basin.
- **Ground disturbed before the baseline window is invisible by construction**, new ruptures, not history. [8]
- **The metric inherits its labels' dating.**
- Ground truth was cross-checked by **four labellers** only.

## In short

- **Challenge**, small, new disturbance, caught early, told apart from seasonal change, on imagery that stays free.
- **Technique**, an unsupervised per-pixel kriging baseline plus accumulated, multi-index evidence.
- **Metric**, onset, coverage, and an error budget with named causes.

*Early warning before the damage is obvious.*

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# References

1. Stubblefield, A., Chandra, S., Eagan, S., et al. (2005). Impacts of gold mining and land use alterations on the water quality of central Mongolian rivers. *Integrated Environmental Assessment and Management*, 1(4), 365-373. <https://doi.org/10.1002/ieam.5630010406>
2. Pecina, V., Juricka, D., Hedbavny, J., et al. (2023). The impacts of mining on soil pollution with metal(loid)s in resource-rich Mongolia. *Scientific Reports*, 13, 2763. <https://doi.org/10.1038/s41598-023-29370-w>
3. Rasmussen, C. E., & Williams, C. K. I. (2006). *Gaussian processes for machine learning*. MIT Press. <https://gaussianprocess.org/gpml/chapters/RW.pdf>
4. Zhu, Z., & Woodcock, C. E. (2014). Continuous change detection and classification of land cover using all available Landsat data. *Remote Sensing of Environment*, 144, 152-171. <https://doi.org/10.1016/j.rse.2014.01.011>
5. Verbesselt, J., Zeileis, A., & Herold, M. (2012). Near real-time disturbance detection using satellite image time series. *Remote Sensing of Environment*, 123, 98-108. <https://doi.org/10.1016/j.rse.2012.02.022>
6. Page, E. S. (1954). Continuous inspection schemes. *Biometrika*, 41(1-2), 100-115. <https://doi.org/10.1093/biomet/41.1-2.100>
7. Earth Genome. (2026). *Mining detector* [Computer software]. GitHub. <https://github.com/earthrise-media/mining-detector>
8. VanderPlas, J. T. (2018). Understanding the Lomb-Scargle periodogram. *The Astrophysical Journal Supplement Series*, 236(1), 16. <https://doi.org/10.3847/1538-4365/aab766>

# Backup: the three detectors, every number

|                                 | GP monitor | z-score   | AMW       |
|---------------------------------|------------|-----------|-----------|
| detections in the scored window | 1,306      | 300       | 55        |
| acquisitions carrying an alert  | 149 of 385 | 44 of 202 | 30 of 386 |
| mine sites ever found           | 8 of 8     | 7 of 8    | 3 of 8    |
| distinct places flagged         | 1,210      | 300       | 7         |
| on-target, + audited mining     | 74.0 %     | 25.7 %    | 85.5 %    |
| on-target by area, labels only  | 61.0 %     | 21.9 %    | 85.5 %    |
| mean detection footprint        | 0.13 ha    | 1.67 ha   | 15.05 ha  |
| total area flagged              | 176 ha     | 501 ha    | 828 ha    |

AMW leads every on-target row and finds 3 sites in eight, on 7 distinct places, while flagging 828 ha. That is the case for reporting coverage beside precision, not instead of it.

# Backup: what was actually run

## MODEL

**48px\_v3.7-ensemble**

9-member CNN, Earth Genome 2024-01-17

## INPUT

**48 × 48 px @ 10 m**

480 m patches, non-overlapping grid

## BANDS

**12-band S2 LIC TOA**

B1–B9, B8A, B11, B12 (B10 dropped)

## COMPOSITE

**± 45 d median**

S2\_HARMONIZED, CLOUD\_SCORE\_PLUS ≥ 0.6

## TIMESTEPS

**597**

our own acquisition grid, 2018–2026

## THRESHOLD

**0.30**

shipped default is 0.50

## OUTPUT

**269 patches**

max confidence 0.670, whole record

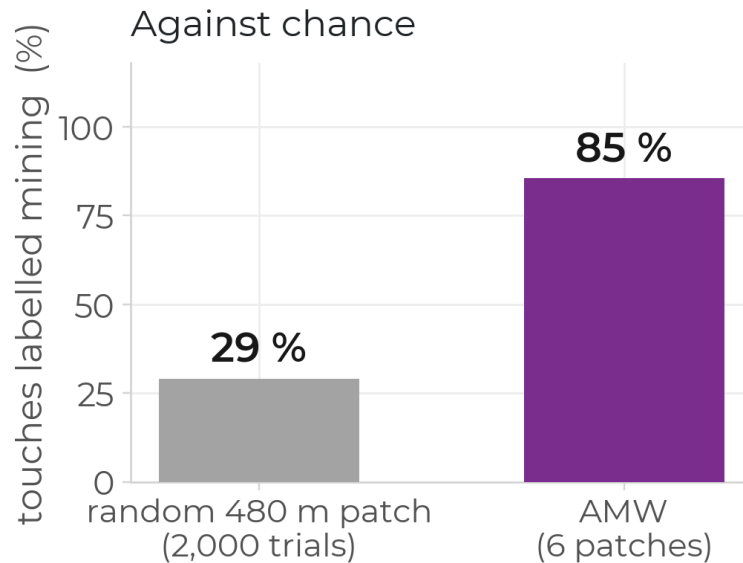
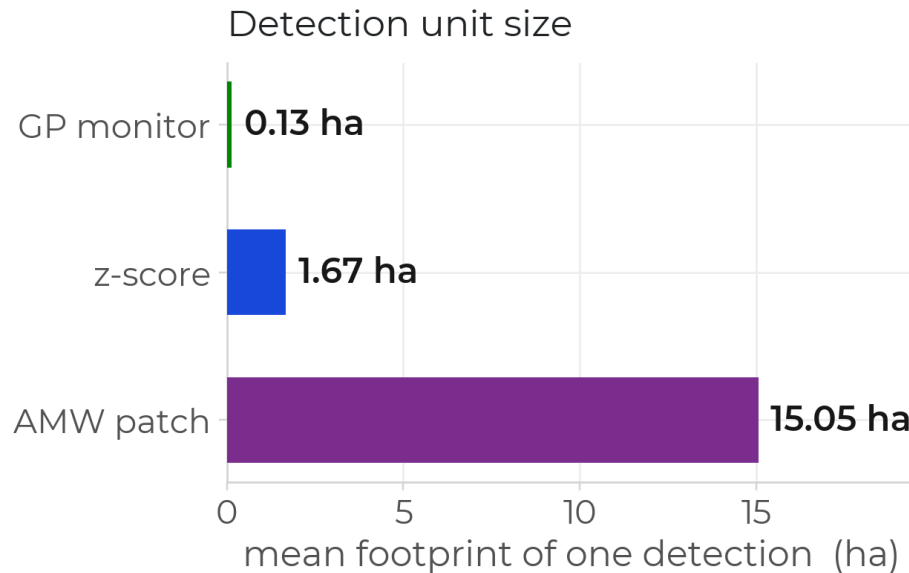
## SCORED

**55 detections**

post-training, 2020-12-30 → 2026-05-06

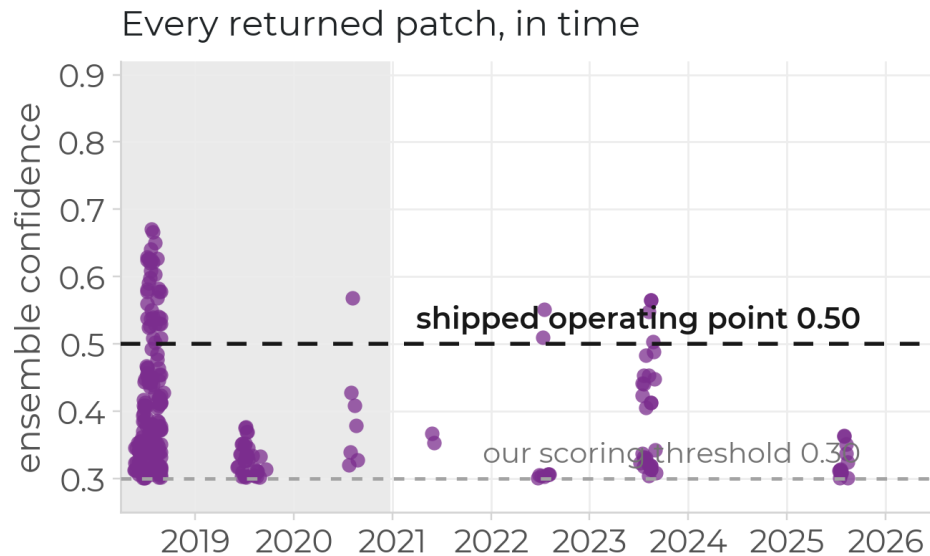
Zero-shot by design: does an Amazon-trained detector transfer to Mongolian steppe placer workings?

# Backup: is 85 % good?

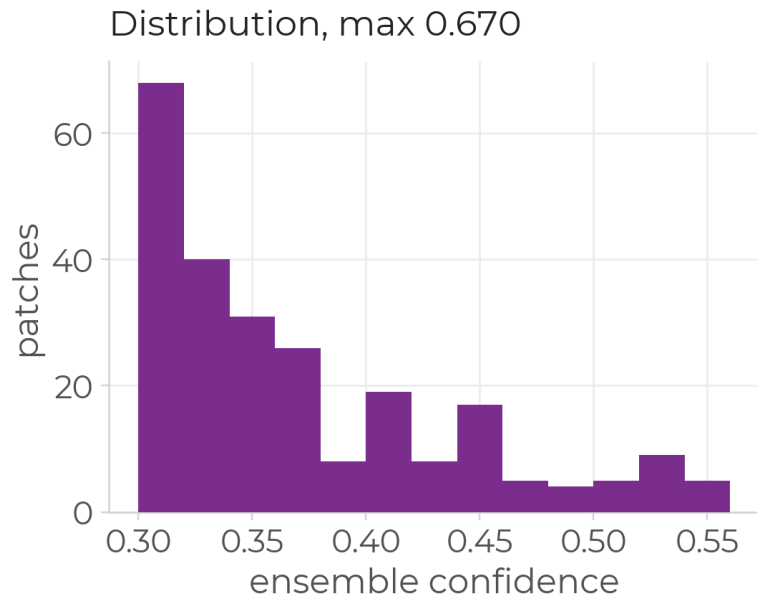


AMW beats chance, with a detection unit 115x larger than ours and 4.7x more ground flagged in total.

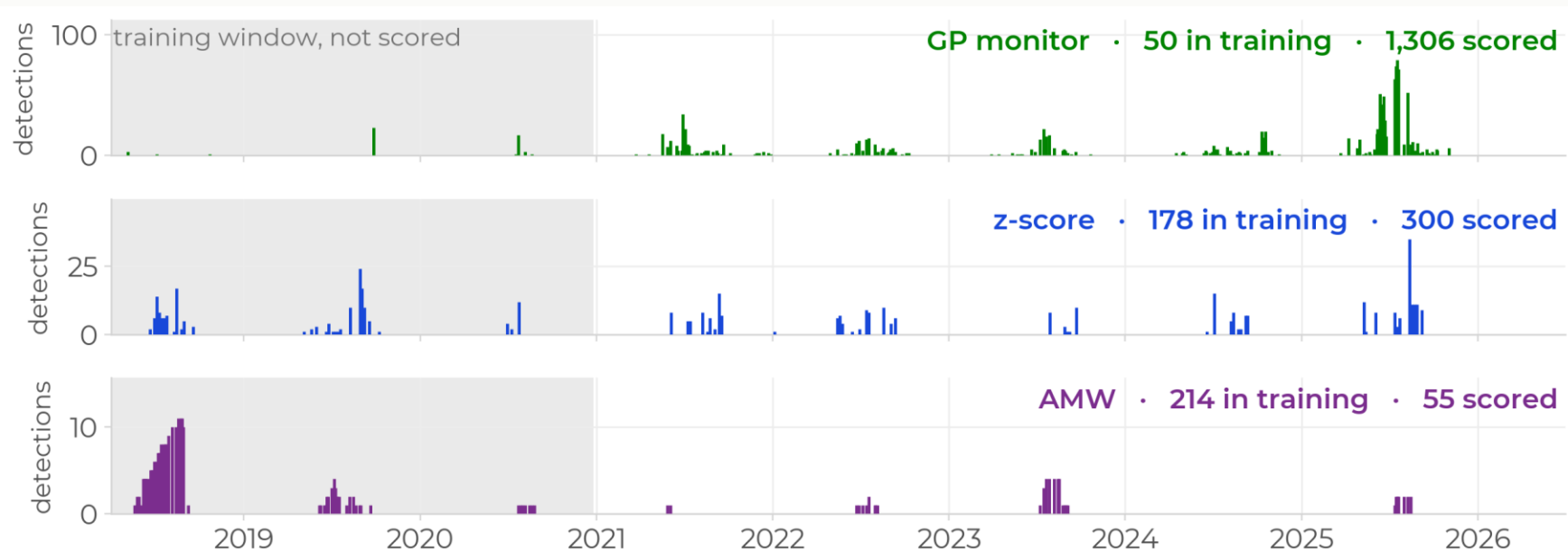
# Backup: it never reaches its own operating point



269 patches cleared 0.30. At its shipped 0.50 it returns almost nothing over this AOI in eight years.

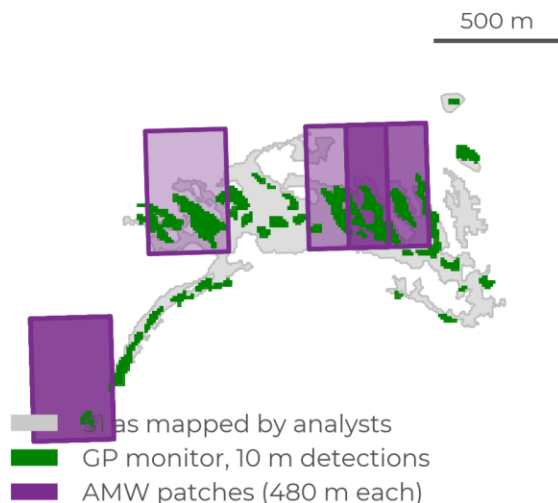


# Backup: when each detector fired



AMW: 70 patches total, 49 in 2018, 15 in 2019, 6 in 2023, none in 2020–22 or 2024–26. The mines grew throughout.

# Backup: the largest site, and when each detector reached it



AMW reaches this site late and covers it with 480 m patches; the comparison of trigger rules above is why we do not claim a timing win here.

## ONSET LAG AT S1, BY TRIGGER RULE

|                         | GP       | AMW    |
|-------------------------|----------|--------|
| any detection           | +17 d    | +304 d |
| $\geq 0.1$ ha on a date | +1,144 d | +304 d |

Under the weak rule we are 48 days early; under the 0.1 ha rule AMW is 452 days earlier. Neither is a fair contest, a 23 ha patch clears a 0.1 ha bar by construction, and our weak onset rests on one small pixel.

## S1 EXTENT

**33.8 ha**

largest of the eight

## AMW AT S2-S8

**never**

no patch intersects them

## Backup: why not IoU?

- **Polygon or spatiotemporal IoU punishes under-coverage**, and under-coverage is the behaviour we deliberately accept.
- An alert needs the **right place, early**. A pretty outline is a different product.
- IoU also **hides the error budget**: a detector can improve its score by growing footprints, which is the opposite of what we want.
- So we score onset, coverage and errors separately.

# Backup: how the error budget was audited

- Off-label detections were **clustered**, and a reviewer gave each cluster a cause on the imagery of the date it fired.
- The audit covers **176 clusters**, not 1,391 individual detections. Off-label detections **inherit the nearest cluster's verdict**.
- That assignment is tight, median **19 m**, p90 **100 m**, max **346 m**, which is why the totals stand.
- Labelling and adjudication were cross-checked by **four labellers**.

# Backup: reproducing the comparison

- Model: `48px_v3.7-ensemble_2024-01-17.h5`, published weights, unmodified.
- Imagery: **downloaded and cached locally**, 597 twelve-band composites, 2.2 GB, not re-queried per run.
- Predictions: one GeoJSON per acquisition, `metric/detections_amw/<date>.geojson`, patch polygons plus confidence.
- Scoring: `metric/scripts/score_amw.py` reuses the same loaders, CRS and cutoff as our own detector; figures from `make_amw_figs.py`.
- Everything above ships in the project bundle.

# Backup: every site, every number

| Site | Extent  | Label dates | Onset lag     | Coverage |
|------|---------|-------------|---------------|----------|
| S1   | 33.8 ha | 5           | +17 d / +2 ts | 24 %     |
| S2   | 30.7 ha | 4           | +7 d / +2 ts  | 14 %     |
| S3   | 15.3 ha | 31          | +9 d / +1 ts  | 48 %     |
| S4   | 3.9 ha  | 4           | +0 d / +0 ts  | 74 %     |
| S5   | 1.8 ha  | 1           | +11 d / +1 ts | 17 %     |
| S6   | 1.5 ha  | 2           | +14 d / +2 ts | 43 %     |
| S7   | 0.8 ha  | 1           | +6 d / +1 ts  | 15 %     |
| S8   | 0.3 ha  | 1           | +0 d / +0 ts  | 36 %     |

## Backup: why the alert needs two acquisitions

- **596 acquisitions**, 2018–2026. Median gap **4 days**, p90 **10 days**, worst **25 days**.
- But **49 % fall Nov–Apr**, snow and low sun, little usable signal for bare ground.
- Per-pixel cloud masking removes more. Two *usable* observations can span weeks.
- By construction: the accumulator must cross threshold with **all four indices agreeing**, one observation cannot trigger it.

## Backup: how the sites were grouped

- 56 dated label snapshots, single-link clustered at **300 m**, named S1–S8 by final extent.
- Geometry only, the grouping does not depend on how anyone named the sites.
- Supersedes an earlier grouping that mixed analyst names with a 500 m rule and produced sites that interleaved along the same river reach.
- Detection-level results, precision, error budget, extent precision, are **unaffected** by the grouping.

## Backup: site by site, overlaid

The next eight slides put the analysts' extent, our detections and the z-score's detections on the same imagery, one site at a time. White dashed outline is the labelled extent in every panel.

# Backup: S1 · 33.8 ha · 24% detected

## S1 · 33.8 ha · we detected 24% of it

White dashed = the analysts' final extent. Onset lag -48 d (-11 acquisitions); 5 label dates.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



# Backup: S2 · 30.7 ha · 14% detected

## S2 · 30.7 ha · we detected 14% of it

White dashed = the analysts' final extent. Onset lag +7 d (+2 acquisitions); 4 label dates.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



# Backup: S3 · 15.3 ha · 48% detected

## S3 · 15.3 ha · we detected 48% of it

White dashed = the analysts' final extent. Onset lag +9 d (+1 acquisitions); 31 label dates.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



# Backup: S4 · 3.9 ha · 74% detected

## S4 · 3.9 ha · we detected 74% of it

White dashed = the analysts' final extent. Onset lag +0 d (+0 acquisitions); 4 label dates.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

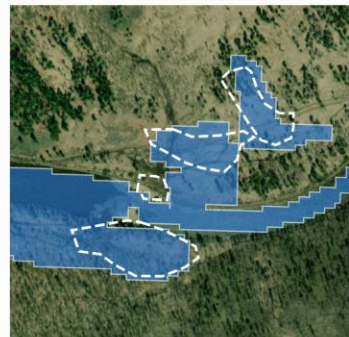
what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



# Backup: S5 · 1.8 ha · 17% detected

## S5 · 1.8 ha · we detected 17% of it

White dashed = the analysts' final extent. Onset lag +11 d (+1 acquisitions); 1 label date.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



# Backup: S6 · 1.5 ha · 43% detected

## S6 · 1.5 ha · we detected 43% of it

White dashed = the analysts' final extent. Onset lag +14 d (+2 acquisitions); 2 label dates.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

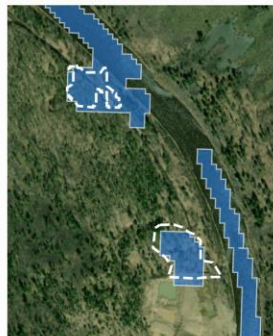
what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



# Backup: S7 · 0.8 ha · 15% detected

## S7 · 0.8 ha · we detected 15% of it

White dashed = the analysts' final extent. Onset lag +6 d (+1 acquisitions); 1 label date.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



# Backup: S8 · 0.3 ha · 36% detected

## S8 · 0.3 ha · we detected 36% of it

White dashed = the analysts' final extent. Onset lag +0 d (+0 acquisitions); 1 label date.

Detections are every post-2021 polygon that touches the site or its surroundings, drawn together.

what the analysts drew



our monitor



z-score baseline



supervised, zero-shot



## Backup: what the false detections actually are

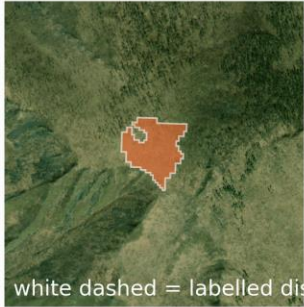
Every off-label detection was clustered and reviewed in context. The next slides show the largest clusters for each cause the reviewers assigned.

# Backup: Cloud and shadow

## Cloud and shadow — 9.6 % of detections

Thin cirrus and haze pass the scene classification mask. A stricter or probabilistic mask, with buffered shadows, is the remedy.

2021-06-28  
3 detections on 2 dates



2021-05-17  
1 detection on 1 date



2021-06-18  
1 detection on 1 date



2020-07-23  
1 detection on 1 date



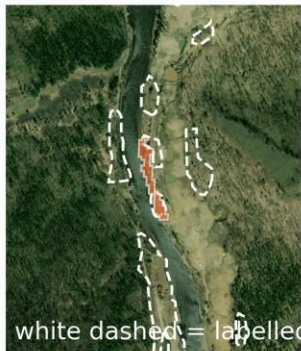
# Backup: River gravel and water

## River gravel and water — 4.0 %

Shifting gravel bars and turbid water on the active channel. A river mask removes these.

2022-06-23

10 detections on 10 dates



2023-07-16

15 detections on 11 dates



2021-09-19

18 detections on 16 dates



2025-04-30

11 detections on 10 dates



# Backup: Off-site, unresolved

## Off-site, cause not resolved — 3.9 %

Off-river, recurring, and not attributable — this is the genuine residual, about 4 % of detections.

2020-07-23

1 detection on 1 date



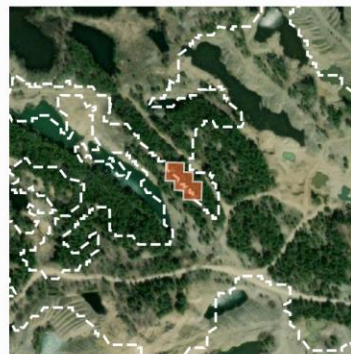
2021-06-28

1 detection on 1 date



2019-09-27

15 detections on 13 dates



2021-07-03

2 detections on 1 date



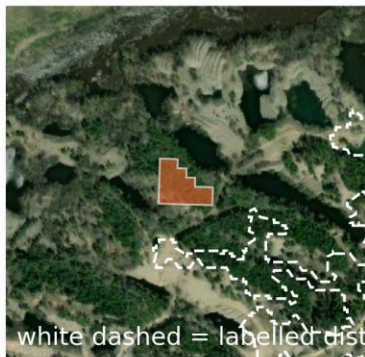
# Backup: Snow and bright ground

## Snow and bright bare ground — 1.8 %

Late-season snow and bright bare ground. Same mask fix as cloud.

2024-10-30

30 detections on 18 dates



2021-12-13

5 detections on 3 dates



2021-11-28

1 detection on 1 date



2021-12-03

1 detection on 1 date



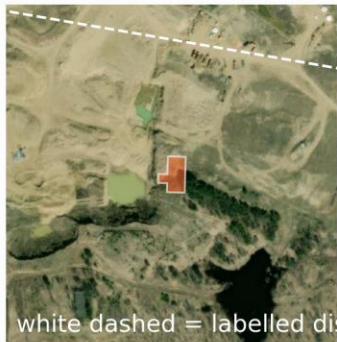
# Backup: Confirmed disturbance outside the labels

## Called real disturbance by the reviewer, outside the labels

These are why the truth set grows: ground the labels missed that a reviewer confirmed as disturbance in context.

2025-07-19

6 detections on 4 dates



2024-08-19

18 detections on 13 dates



2025-06-05

30 detections on 12 dates



2025-06-12

14 detections on 10 dates

